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Centre de Mise en Forme des Matériaux

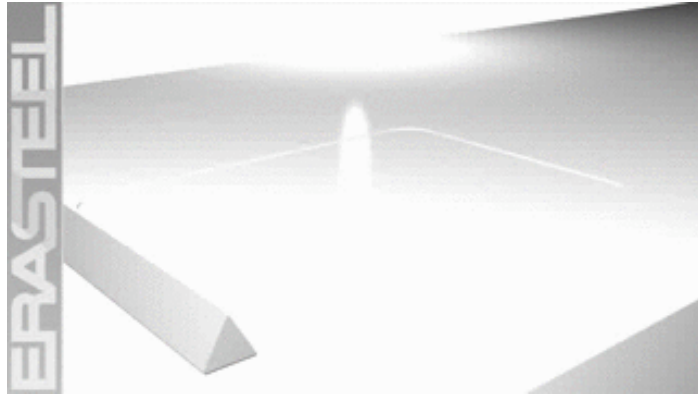


# Numerical simulation of additive manufacturing processes by Laser Beam Melting : Thermomechanical features

Qiang CHEN, Yancheng ZHANG, Gildas GUILLEMOT,  
Charles-André GANDIN, Michel BELLET

JOURNEE SNS – CFV,  
Synergies de Simulation entre Fabrication Additive et Soudage  
*EDF Laboratoire Paris-Saclay, 26 Juin 2018*

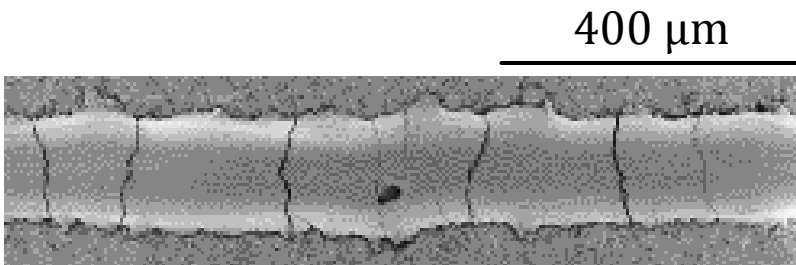
## ▶ Laser Beam Melting (LBM)



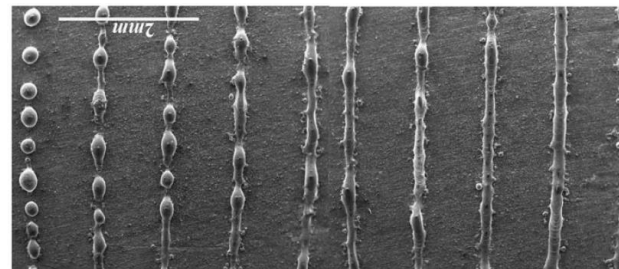
### Advantages

- Direct manufacturing of complex shape geometries based on CAO-models pieces
- Decrease of the duration time required in the design to manufacturing cycle
- Limitation of the final stages processes
- Wide range of material for application
  - metallic (Aluminium, Titanium, Nickel, Steel ...)
  - ceramic (Alumina / Zirconia)

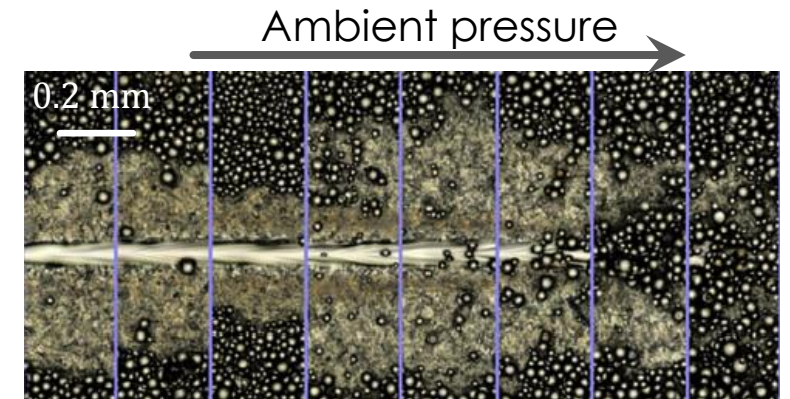
## ▶ ... with some defects



Cracks on alumina  $Al_2O_3$   
[L. Moniz Da Silva Sancho,  
CdM, CEFALE Project]

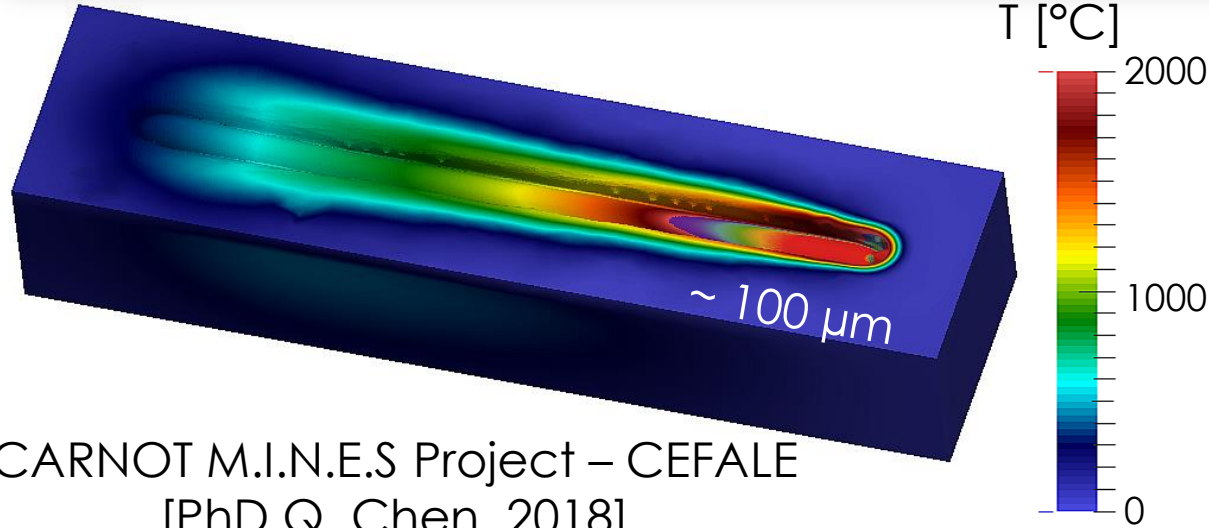


Melt pool instabilities - 316L  
*Balling effects* [Li, 2012]



Denudation, Ti-6Al-4V  
[Matthews, 2016]

# Simulations – Level Set approaches [CEMEF]



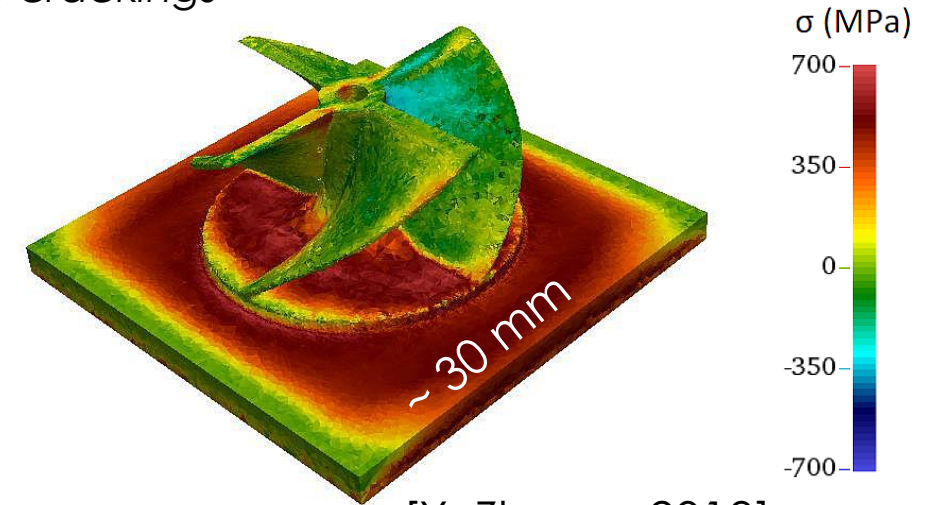
CARNOT M.I.N.E.S Project – CEFALE  
[PhD Q. Chen, 2018]

## ► Scale of the piece geometry : **Macro-**

- Objectives : **To optimize the building strategy**
  - **Temperature field** on the whole piece
  - **Strain and stress field**, developed during process and after cooling (residual stress)
  - Thermal and mechanical effects of the **supports**
  - Development of the **macrostructure** (size and grain texture)
  - **Defects** formed at macro-scale as cracks developments in solid state (cooling)

## ► Scale of the track development : **Meso-**

- Objectives : **To master LBM process**
  - **Laser / powder bed interaction** – Heat source definition
  - **Track geometry** after melting / solidification
  - **Microstructure** evolution (phase transformation and associated segregation in rapid solidification)
  - **Stress** induced in the back part of the melt pool
  - **Defects** at micro-scale as *track irregularities, porosities and hot crackings*

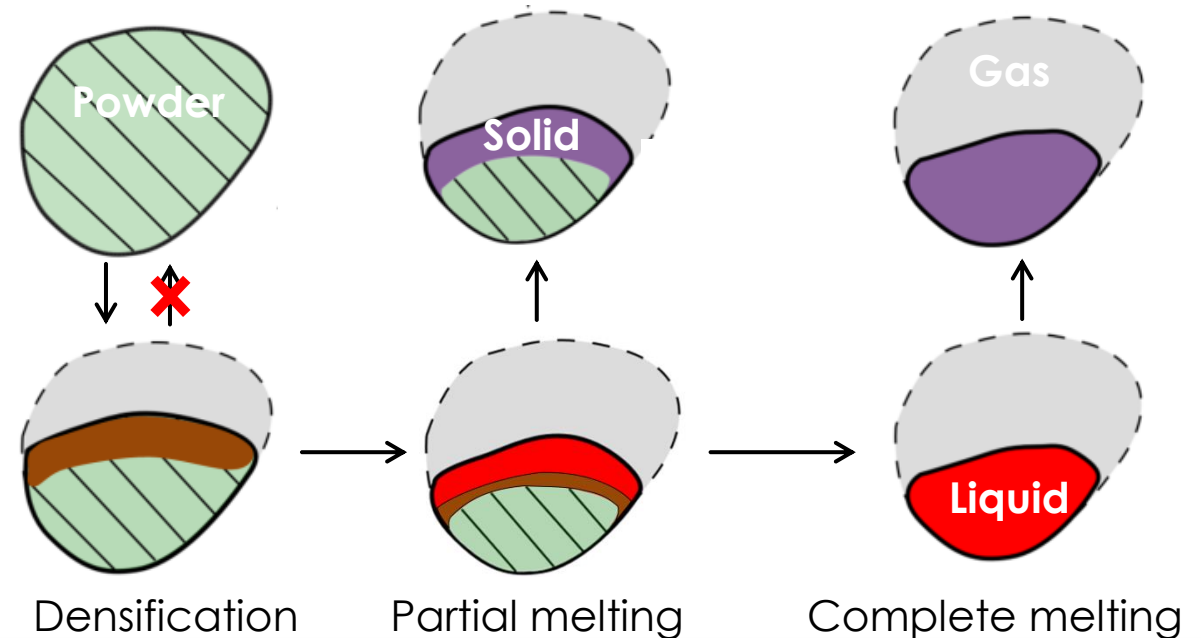
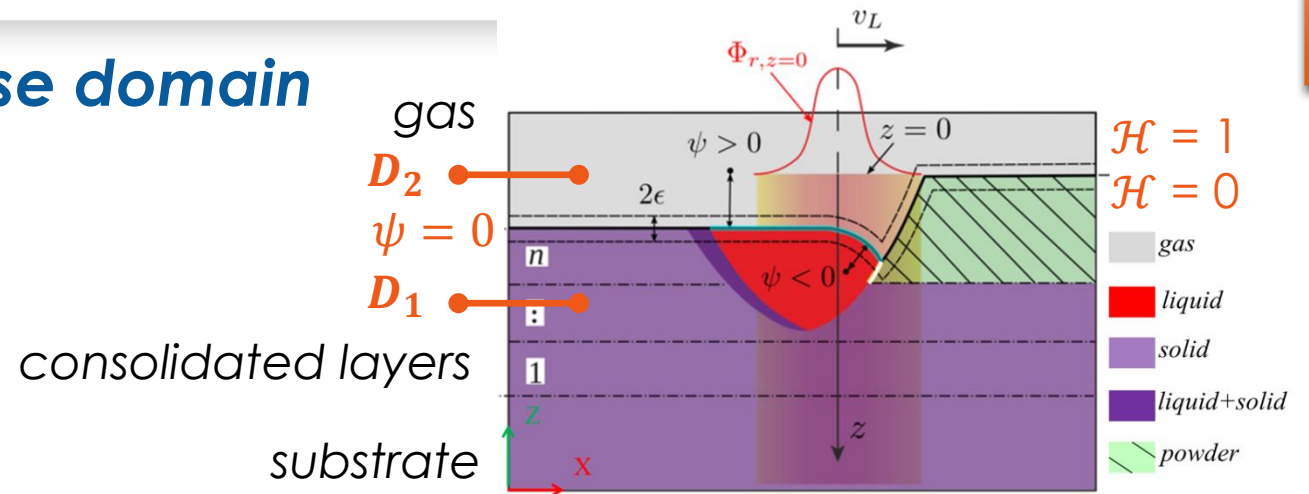


[Y. Zhang, 2018]

## ► Level set approach – Multiphase domain

### ■ System definition

- Multi-domain,  $D_i, i \in \{1,2\}$ 
  - Single-phase domain  $D_2$ : gas
  - Multi-phase domain  $D_1$ :  $\alpha_j$
- Interdomain boundary  $D_1/D_2$ 
  - Level set signed distance function  $\psi$ , depending from the position of the  $D_1/D_2$  interface where  $\psi = 0$
  - Heaviside function  $\mathcal{H}$  with the half-thickness transition domain  $\epsilon$  and associated Dirac function  $\delta = \partial\mathcal{H}/\partial\psi$
- Averaged approach
  - System scale :  $\{\chi\} = \sum_i \mathcal{H}^{D_i} \langle \chi \rangle^{D_i}$
  - Domain scale :  $\langle \chi \rangle^{D_i} = \sum_j g_{D_i}^{\alpha_j} \chi^{\alpha_j}$





## ► Heat conservation equation

$$\frac{\partial\{\rho h\}}{\partial t} + \nabla \cdot (\{\rho h\}\mathbf{u}) - \nabla \cdot (\{\lambda\}\nabla T) = \dot{q}_L - \dot{q}_r$$

## Heat loss (radiation)

$$\dot{q}_r = \delta\sigma_r\epsilon_r(T^4 - T_{ext}^4)$$

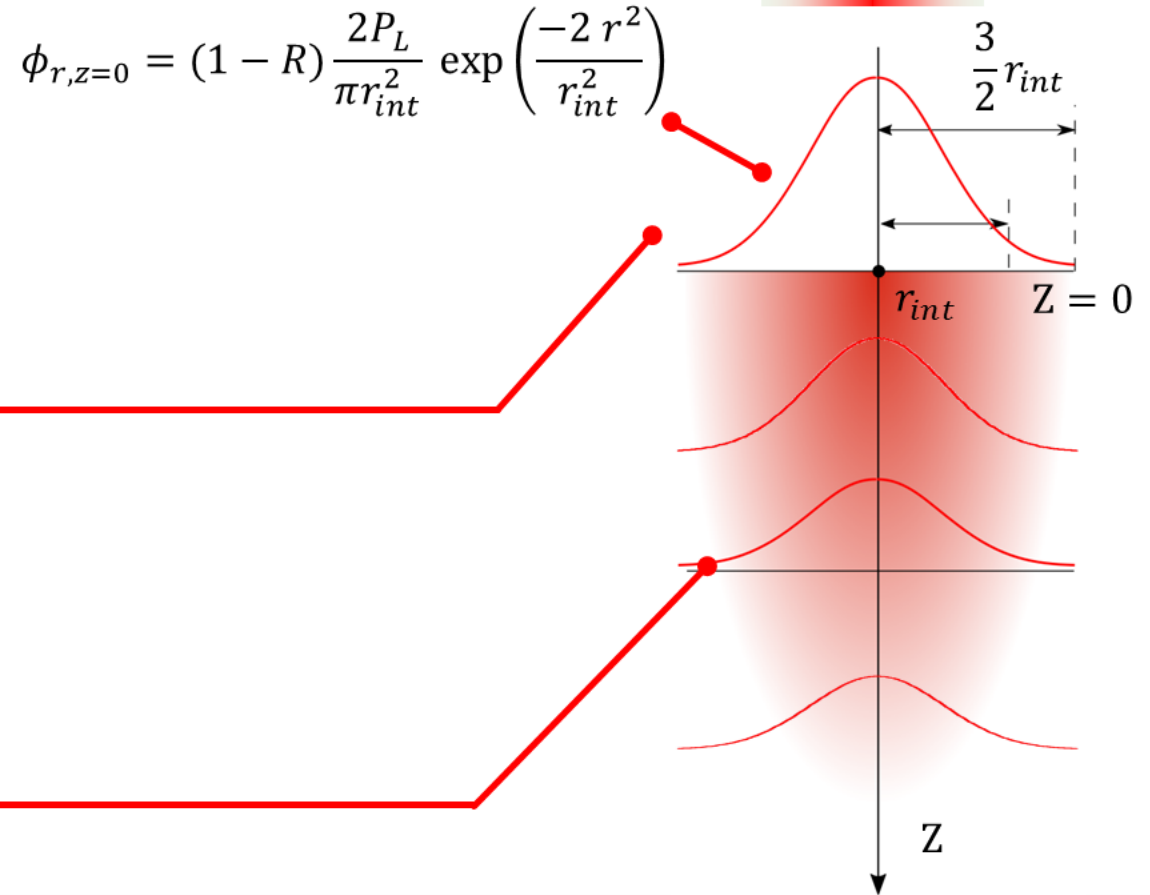
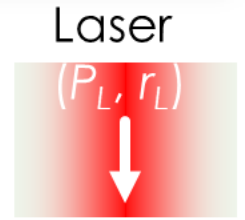
## ► Heat source / Laser

### ■ Laser source $\dot{q}_L$

- Gaussian surface distribution  $\phi_{r,z=0}$
- Volume heat source / Beer-Lambert model

$$\frac{d\phi}{dz} = -\alpha\phi \Rightarrow \phi(r, z) = \phi_{r,z=0} \exp\left(-\int_0^z \alpha dl\right)$$

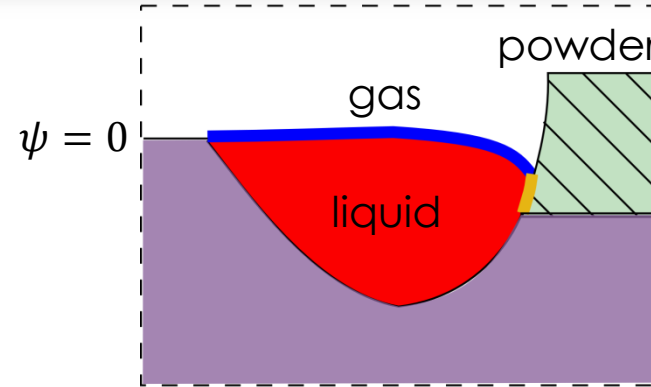
$$\dot{q}_L = -\frac{d\phi}{dz} = \phi_{r,z=0} \cdot \alpha \cdot \exp\left(-\int_0^z \alpha dl\right)$$



## ► Navier – Stokes equation

$$\{\rho\} \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) - \nabla \cdot \underline{\underline{\sigma}} = \mathbf{f}_V$$

$$\nabla \cdot \mathbf{u} = \dot{\theta} = -\frac{1}{\rho} \frac{d\rho}{dt}$$



Surface tension & Marangoni force imposed on both the **liquid/gas** interface & the **liquid/powder** boundary

■ Compressible Newtonian behaviour :

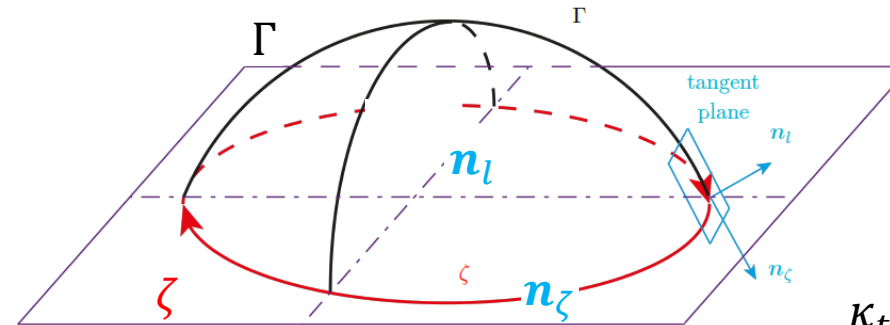
$$\begin{cases} \underline{\underline{\sigma}} = 2\eta \left( \underline{\underline{\dot{\epsilon}}} - \frac{1}{3} \text{tr}(\underline{\underline{\dot{\epsilon}}}) \underline{\underline{I}} \right) - p \underline{\underline{I}} \\ \text{tr}(\underline{\underline{\dot{\epsilon}}}) = \nabla \cdot \mathbf{u} = \dot{\theta} \end{cases}$$

■ Volumetric force  $\mathbf{f}_V$  :

• Gravity :  $\{\rho\} \mathbf{g}$

• Surface tension :  $\mathbf{f}_s = \gamma \kappa_t \mathbf{n}_l$

• Marangoni force :  $\mathbf{f}_M = \frac{\partial \gamma}{\partial T} \nabla_s T$  with  $\nabla_s T = \nabla T - (\nabla T \cdot \mathbf{n}_l) \mathbf{n}_l$  ( $\times \delta$ ) [Brackbill 1992]



Semi-implicit implementation of **surface tension**  
[Hysing, 2005, Hamide, 2008, Khalloufi, 2016]

$$\kappa_t \mathbf{n}_l = (\kappa_t \mathbf{n}_l)^- + \nabla_s \cdot (\nabla_s \mathbf{u}) \Delta t$$

Explicit Stabilization

■ Transport and reinitialization of level set field :  $\frac{d\psi}{dt} = \frac{\partial \psi}{\partial t} + \mathbf{u} \cdot \nabla \psi = 0$

Geometrical reinitialization with respect to  $\psi = 0$  [Shakoor, 2015]

## ► Equilibrium

$$\nabla \cdot \underline{\underline{\sigma}} + \{\rho\} \mathbf{g} = 0$$

### ■ Behavior law

#### ■ Dense medium

- Elasto-Viscoplastic (EVP), if  $T < T_s$

$$\underline{\underline{\dot{\epsilon}}} = \underline{\underline{\dot{\epsilon}}}^{el} + \underline{\underline{\dot{\epsilon}}}^{vp} + \underline{\underline{\dot{\epsilon}}}^{th}$$

$$\bar{\sigma} = \sigma_Y + K(\sqrt{3})^{m+1} \bar{\epsilon}^n \dot{\epsilon}^m$$

- Visco-Plastic (VP), if  $T_s \leq T \leq T_l$

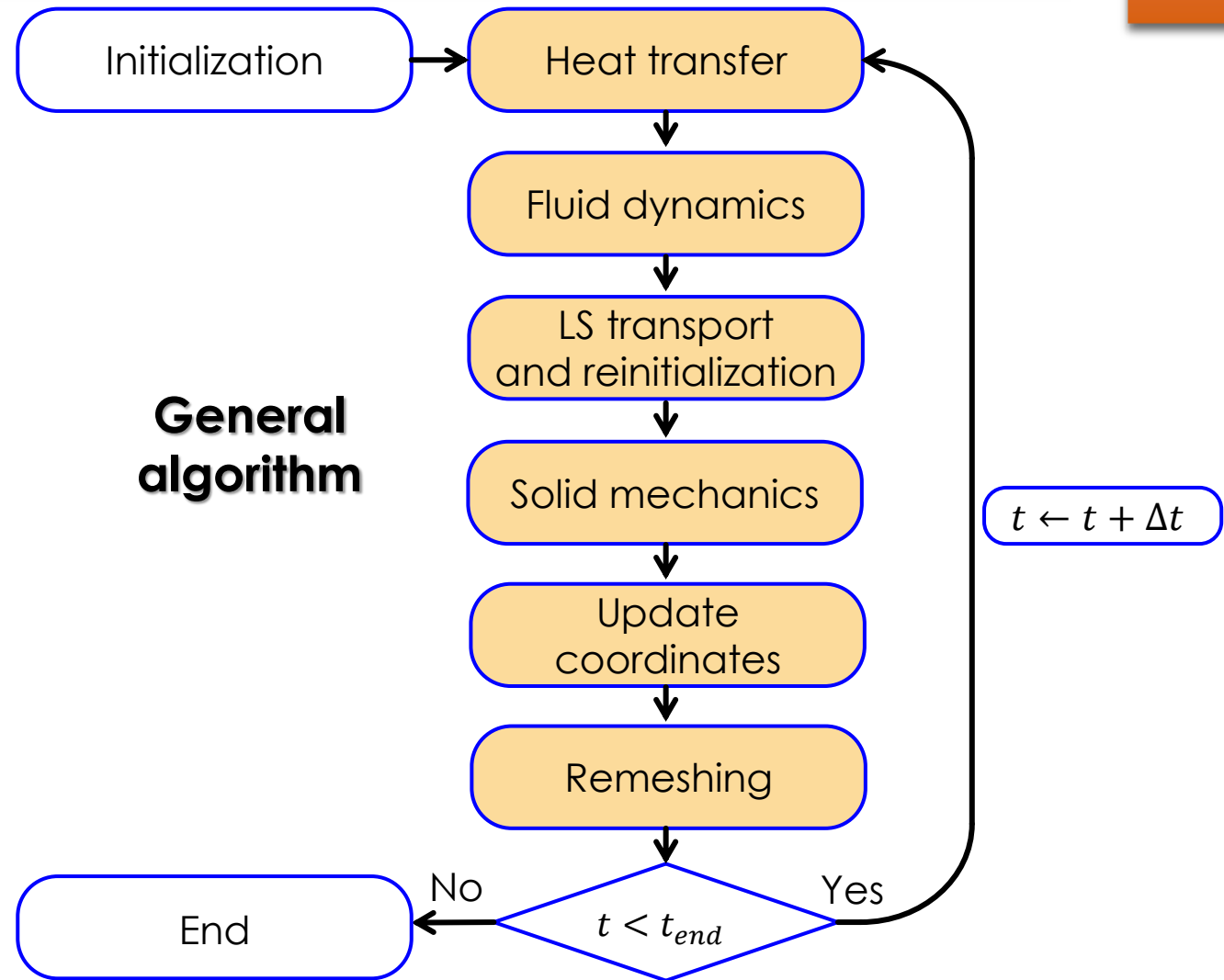
$$\underline{\underline{\dot{\epsilon}}} = \underline{\underline{\dot{\epsilon}}}^{vp} + \underline{\underline{\dot{\epsilon}}}^{th}$$

$$\bar{\sigma} = K(\sqrt{3})^{m+1} \bar{\epsilon}^m$$

- Newtonian (N), if  $T > T_l$

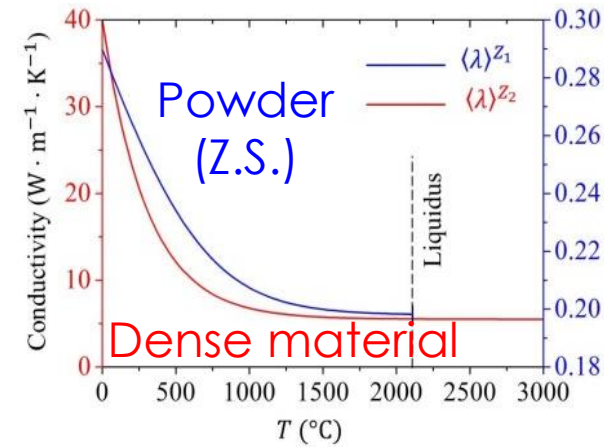
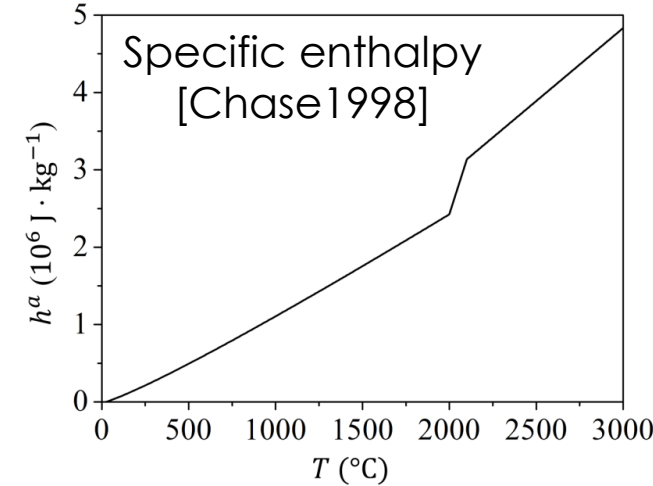
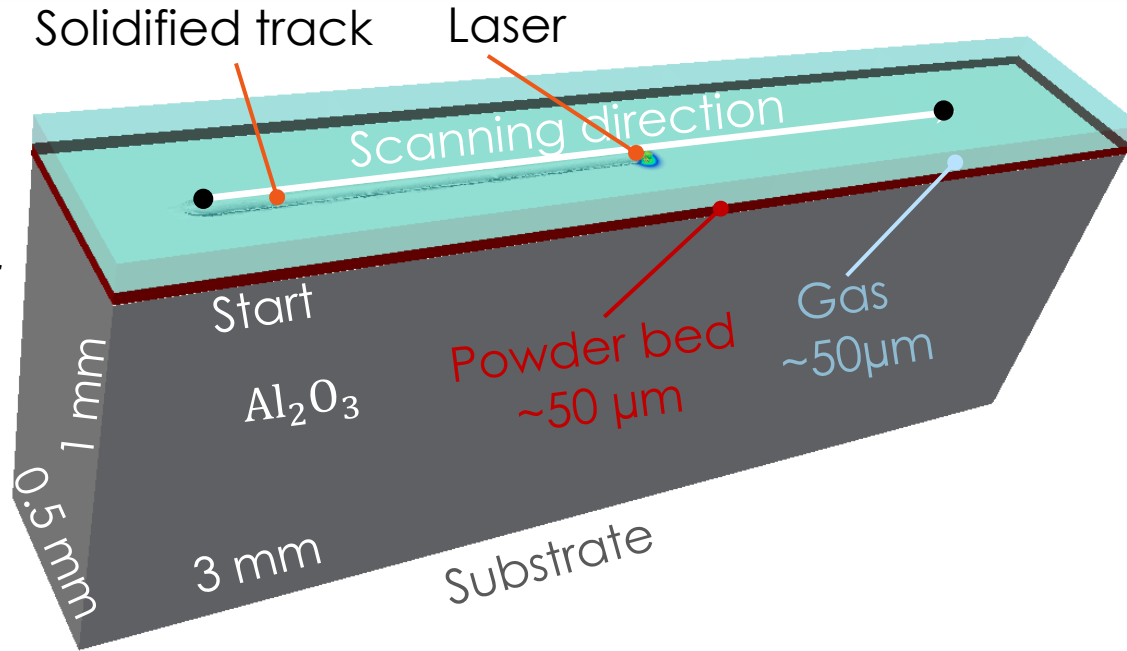
#### ■ Gas and powder

- Newtonian (N)



# Application – Track development

## ► Configuration



[Zehner, 1970]

- Absorption
  - Solid and powder  $\alpha_s$
  - Liquid  $\alpha_l$
- Emissivity  $\epsilon_r = 0.4$  (radiation on gas/material boundary)
- Initial and ambient temperature :  $T_0 = 20 \text{ °C}$

Face	Thermal	Fluid	Solid
Bottom	$h_T = 40 \text{ W} \cdot \text{m}^{-2} \cdot \text{K}^{-1}$	$u = 0$	$u = 0$
Lateral		$u \cdot n = 0$	Free
Top	Adiabatic	Free	



# Application – Fluid flow evolution

## Fluid dynamics in melt pool

$$\frac{\partial \gamma}{\partial T}$$

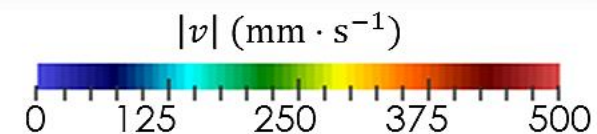
( $\times 10^{-5} \text{N} \cdot \text{m}^{-1} \cdot \text{K}^{-1}$ )

$$P_L = 84 \text{ W}$$

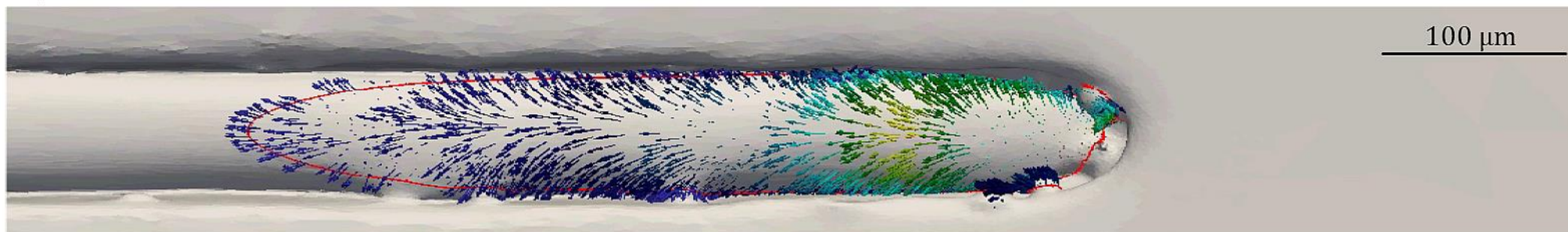
$$v_L = 200 \text{ mm} \cdot \text{s}^{-1}$$

$$r_{int} = 37.5 \text{ } \mu\text{m}$$

$$\alpha_s = \alpha_l = 5 \text{ mm}^{-1}$$



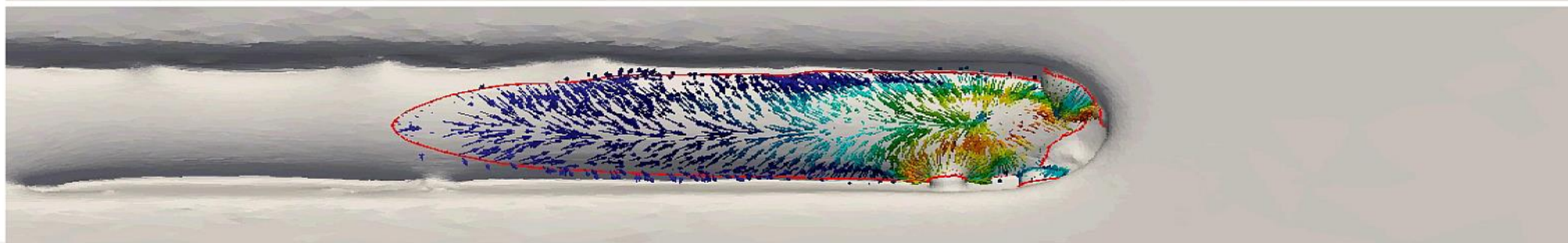
– 8.2  
(Nominal value)



– 48



+ 48



Fluid flow directions highlighted / Higher centrifugal (centripetal) convection flow caused by higher negative (positive)  $\partial \gamma / \partial T$



# Application – Balling effect

- Irregularity on liquid interface

$v_L$   
( $\text{mm}\cdot\text{s}^{-1}$ )

$P_L = 84 \text{ W}$

$r_{int} = 37.5 \mu\text{m}$   
 $\alpha_s = \alpha_l = 5 \text{ mm}^{-1}$

Black contour (solidus,  $T_s = 2004 \text{ }^\circ\text{C}$ )  $v_L$

( $\text{mm}\cdot\text{s}^{-1}$ )  
31 6L stainless steel

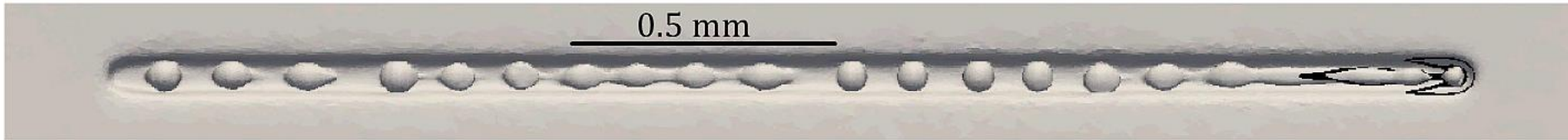
550



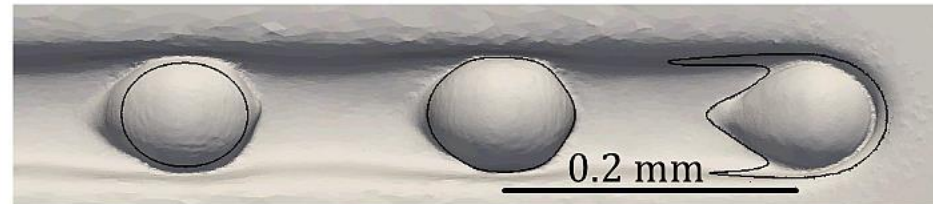
600



800



600



50

150

200

250

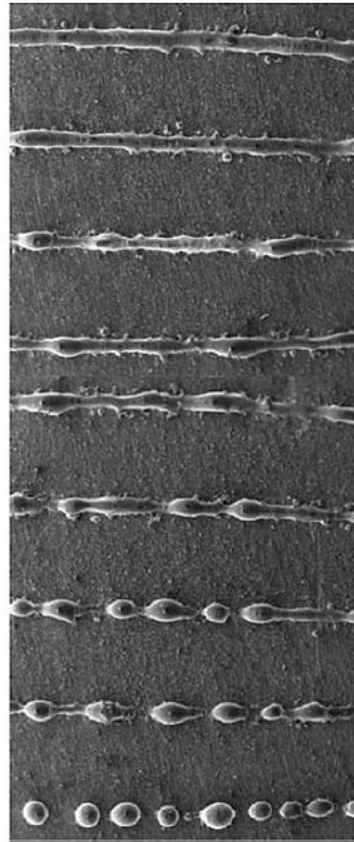
300

350

400

450

500



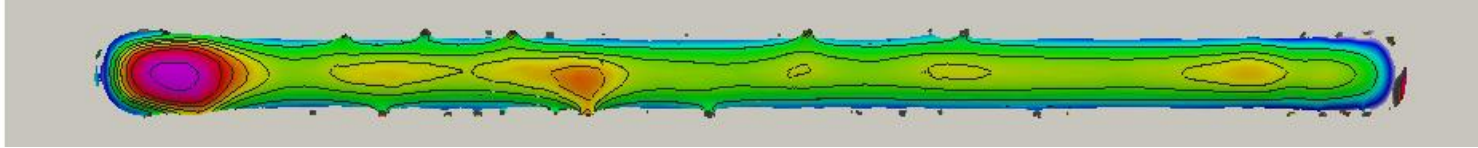
[Li, 2012]

Transition from continuous to interrupted track with increasing  $v_L$ , leading to balling

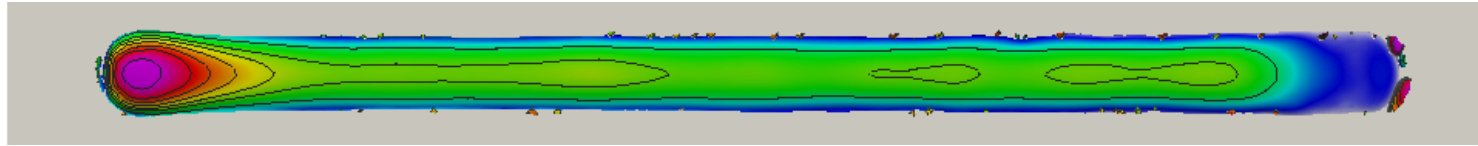
# Application – Irregularities

## Track height variation

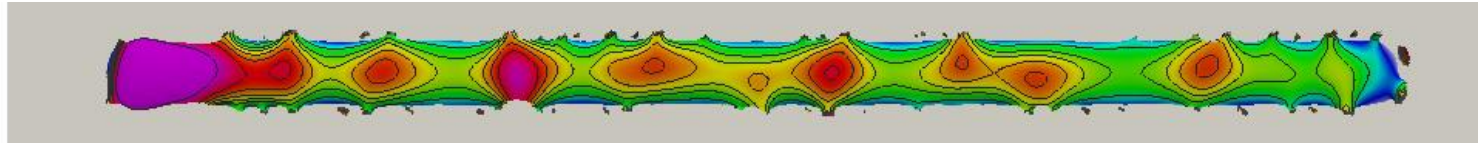
$$\frac{\partial\gamma}{\partial T} = -8.2 \times 10^{-5} \text{ N} \cdot \text{m}^{-1} \cdot \text{K}^{-1}$$



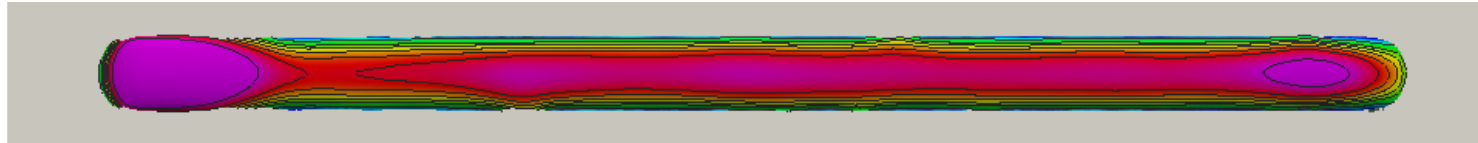
$$\frac{\partial\gamma}{\partial T} = -48 \times 10^{-5} \text{ N} \cdot \text{m}^{-1} \cdot \text{K}^{-1}$$



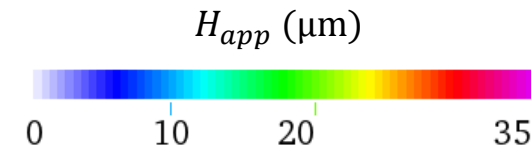
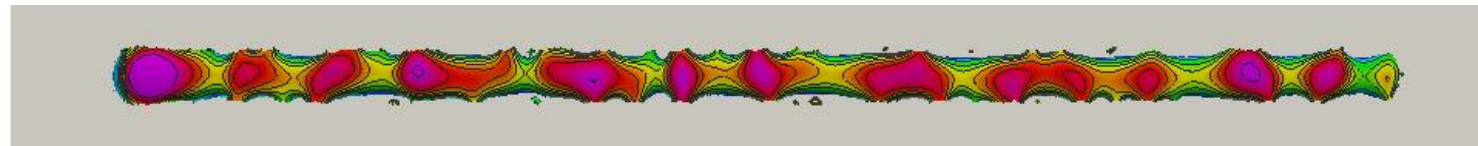
$$\frac{\partial\gamma}{\partial T} = +48 \times 10^{-5} \text{ N} \cdot \text{m}^{-1} \cdot \text{K}^{-1}$$



Higher liquid viscosity  
 $0.2 \text{ Pa} \cdot \text{s}$



Double scanning  
speed  $400 \text{ mm} \cdot \text{s}^{-1}$



500  $\mu\text{m}$

500  $\mu\text{m}$

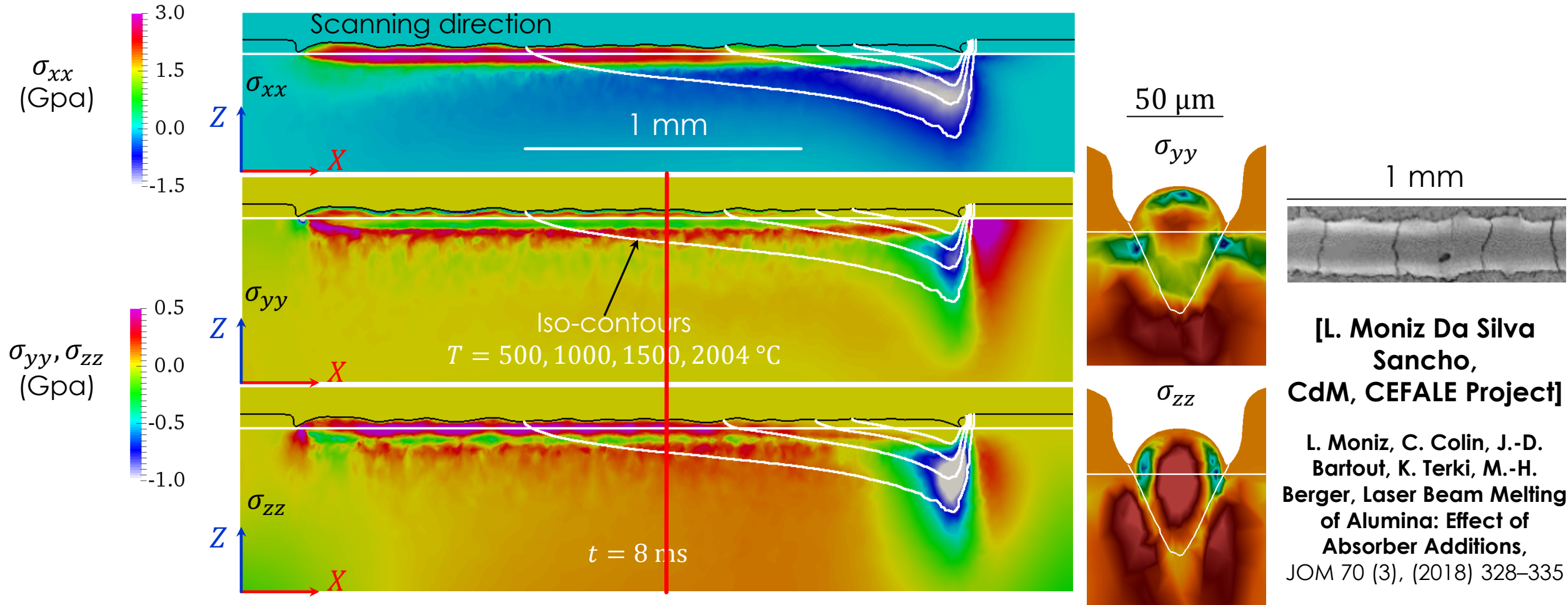
Higher negative  $\partial\gamma/\partial T$  or viscosity  $\rightarrow$  less surface height variation  
Higher positive  $\partial\gamma/\partial T$  or scanning speed  $\rightarrow$  more surface height variation

# Application – Stress distribution

## Stress distribution

$$P_L = 84 \text{ W} \quad r_{int} = 50 \text{ }\mu\text{m}$$

$$v_L = 300 \text{ mm} \cdot \text{s}^{-1} \quad \alpha_s = \alpha_l = 5 \text{ mm}^{-1}$$



[L. Moniz Da Silva Sancho, CdM, CEFALE Project]

L. Moniz, C. Colin, J.-D. Bartout, K. Terki, M.-H. Berger, Laser Beam Melting of Alumina: Effect of Absorber Additions, JOM 70 (3), (2018) 328–335

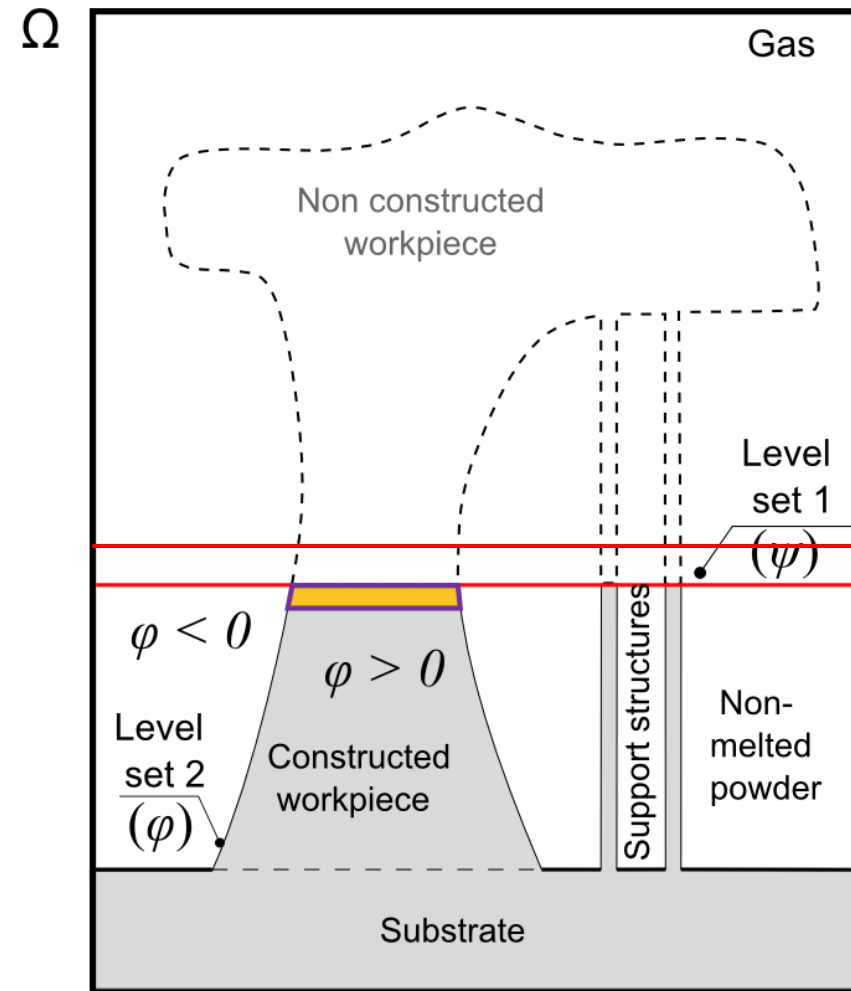
Higher  $\sigma_{xx}$  and  $\sigma_{zz}$  → more risk of cracks  $\perp$  scanning direction and delamination



## ► Principles

- Starting point: **CAD** of **the part** to be built, completed by **the substrate** and the possible **supports**
- Mesh of this **CAD** and immerse in a **background mesh  $\Omega$**
- Construct the conform mesh at interfaces:
  - material / gas
  - constructed part/ non-exposed powder
- Over time, the **level set  $\psi$**  is updated progressively through the mesh **layer by layer** or **fraction of layer**
- Resolve the **thermal** and **mechanical** problems in each time steps:
  - in the part under construction...
  - ... but also in the non-exposed powder

Schematic of Macro-Scale modelling



[Y. Zhang]

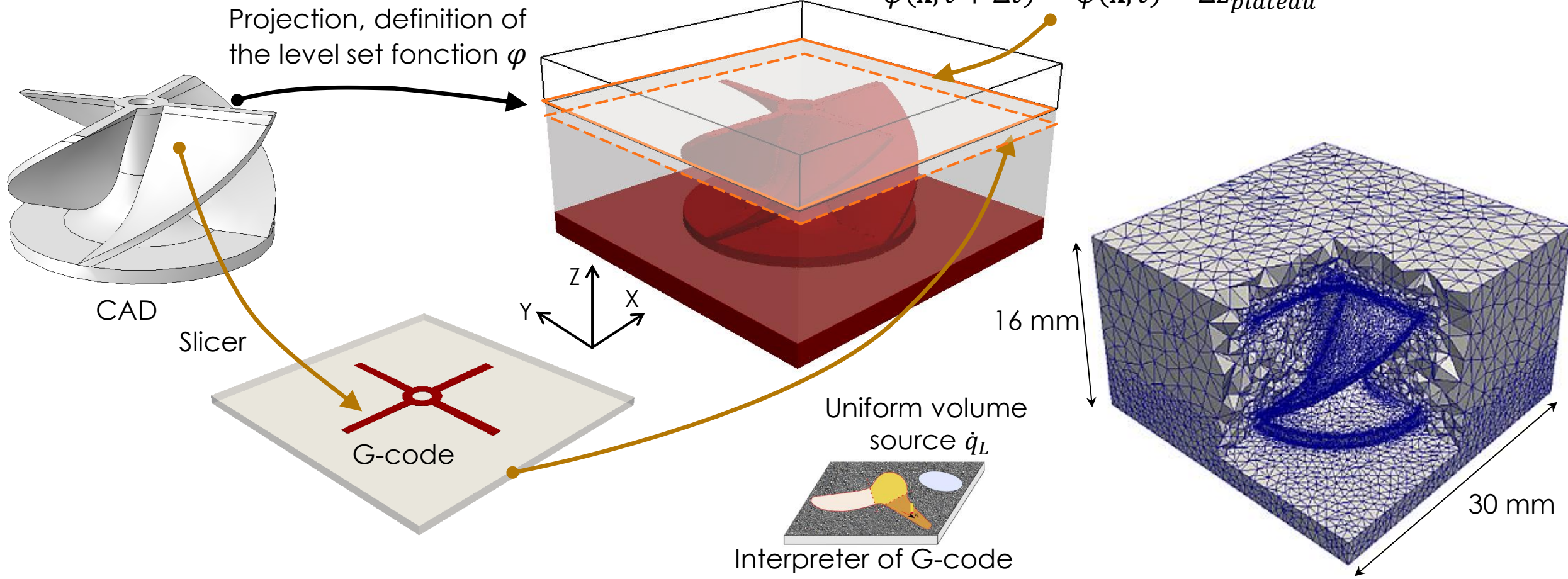


# Strategy – Overview

## ► Example : Impeller structure

Update the construction level set function:

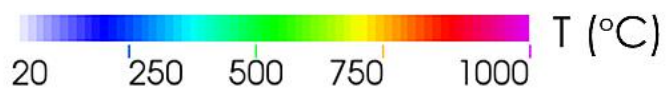
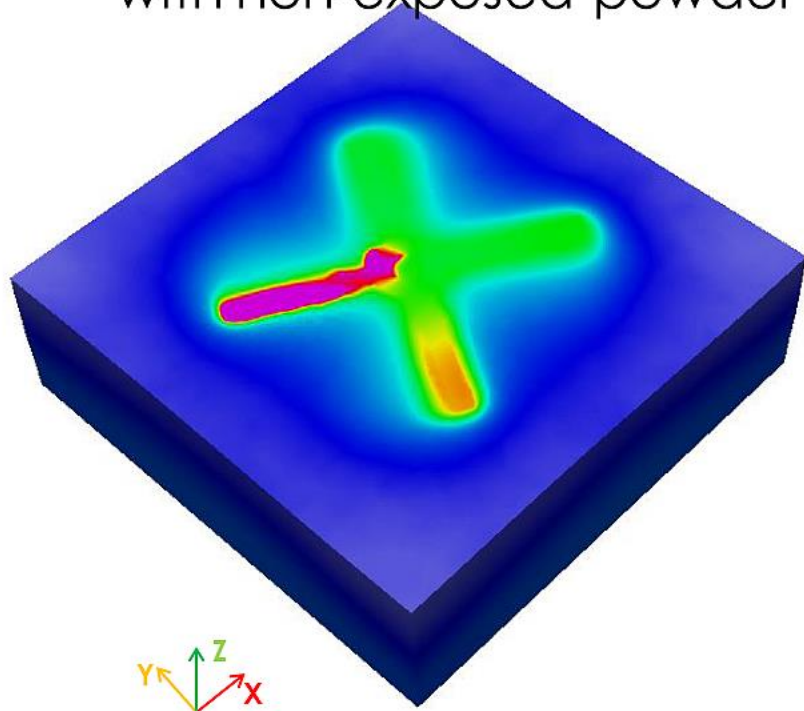
$$\psi(\mathbf{x}, t + \Delta t) = \psi(\mathbf{x}, t) - \Delta z_{plateau}$$



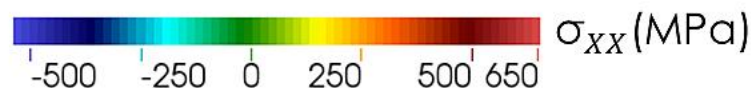
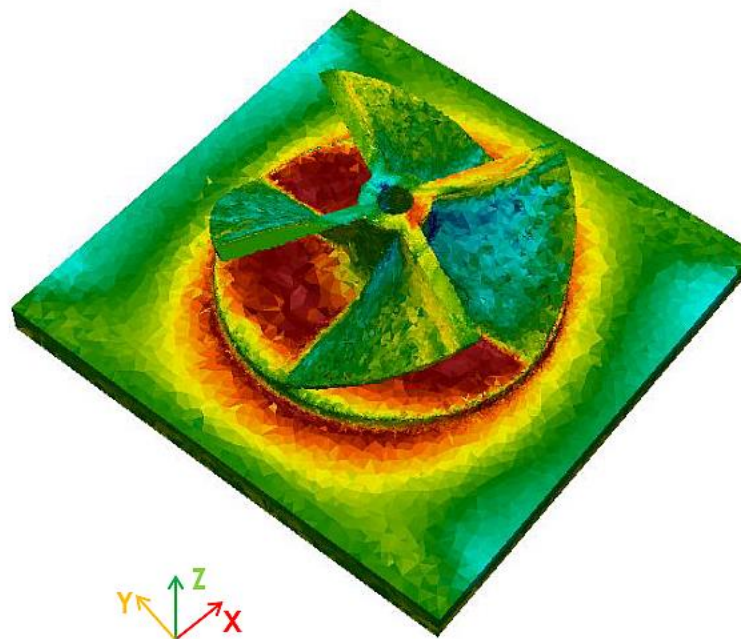
# Application – Temperature and Stress fields

► **In718 part** : Temperature and stress distribution during the construction process (50 layers)

■ Temperature:  
with non-exposed powder

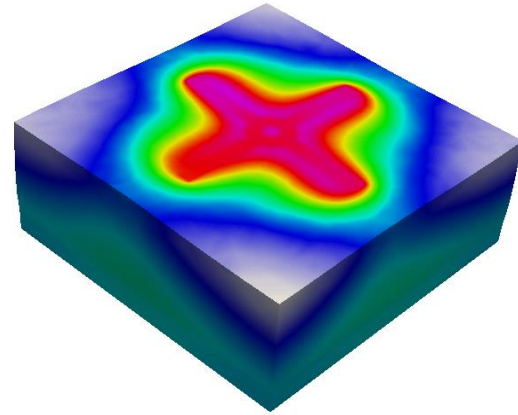


■ Stress:  
without non-exposed powder

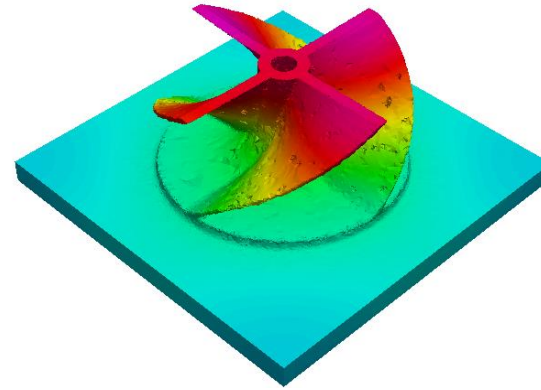


# Application – Temperature and Stress fields

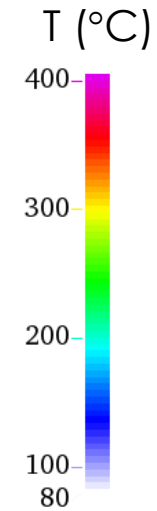
## ► **Final construction: temperature**



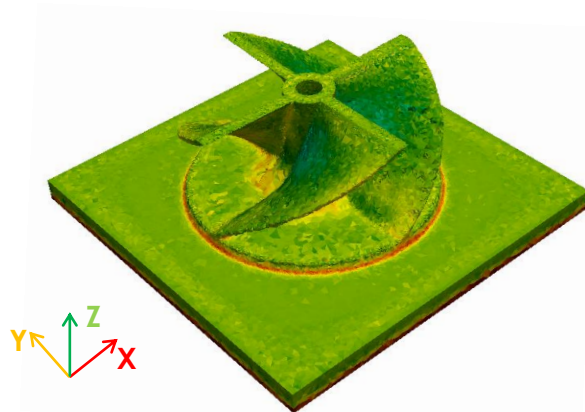
Part + non-exposed powder



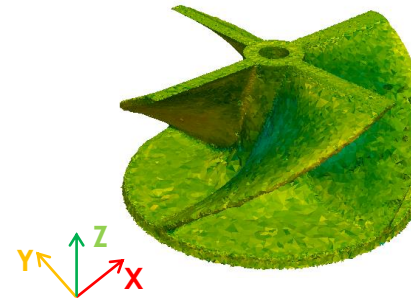
Part



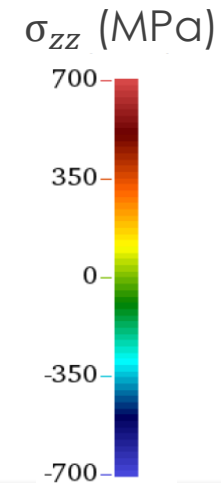
## ► **Final construction + 2h: residual stress**



Cool down to room temperature



After removing from the substrate





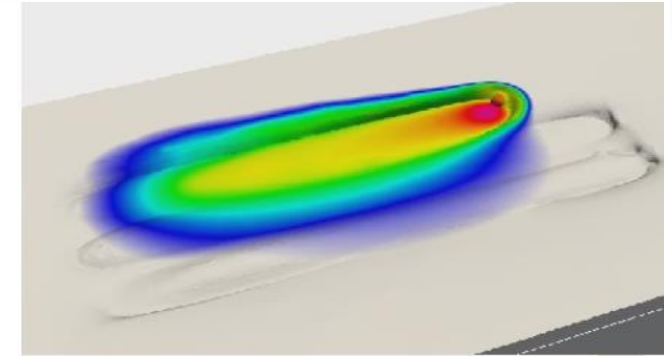
# ... Ongoing and Future Projects

## ▶ **PhD CIFRE SAFRAN (A. Queva) (2017-2020)**

(PIMM, I2M)

### ■ **Laser Beam Melting process applied onto metallic materials**

- Laser / metal interaction and associated effects at meso-scale
- Energy absorption, fluid flow evolution and vaporisation



## ▶ **PhD MACCADAM (ANR – 2018-2021)**

(LMGC, ICA, LGP, Poly-Shape)

### ■ **Controlled characteristics materials produced by WAAM**

- Optimization of process parameters and building strategy
- Coupling between and meso- and macro- scale approaches



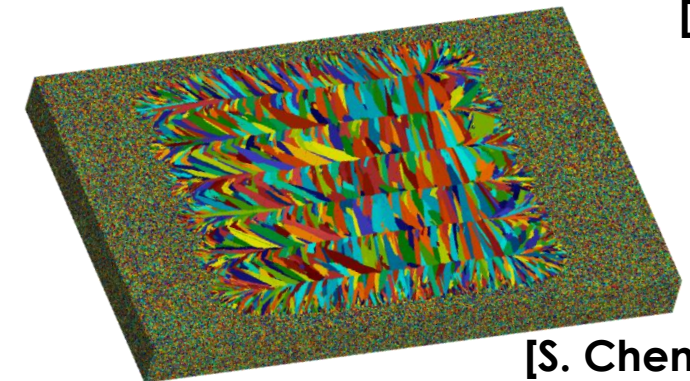
[LMGC]

## ▶ **PhD NEMESIS (ANR – 2018-2021)**

(LMGC, ICB, CEA List, Arcelor Mittal, EDF R&D, Transvalor)


### ■ **Numerical metallurgy supporting arc welding processes**

- Predictions of cracks and brittle phase developments
- Application to NDT technologies in welding process



[S. Chen, CEMEF]

The thermo-mechanical analysis is performed for the **meso**- and **macro**-scale models under the **level-set** framework with **finite element** method:

	Meso-scale	Macro-scale
Temperature	Track	Whole part
Non-melted powder	Yes	Yes
Melt pool dynamics + shape		-
Mesh adaptation	Error estimation – total element number control	User defined – size control
Stress	Hot stress	Hot stress + Residual stress
Distortion	-	Yes
Complex geometry	-	Yes